

26/03/2015

WATER BODIES V2 ALGORITHM

USING PROBA-V 10 day mean composites multispectral data



Water Bodies V2 – PROBA-V





μ-satellite, gap filler SPOT <-> Sentinel

PROBA-V S1-TOC synthesis products

- full daily coverage: Lat. 35°N and 75°N Lat. 35°S and 56°S
- full coverage every 2days at the equator
- spectral bands:

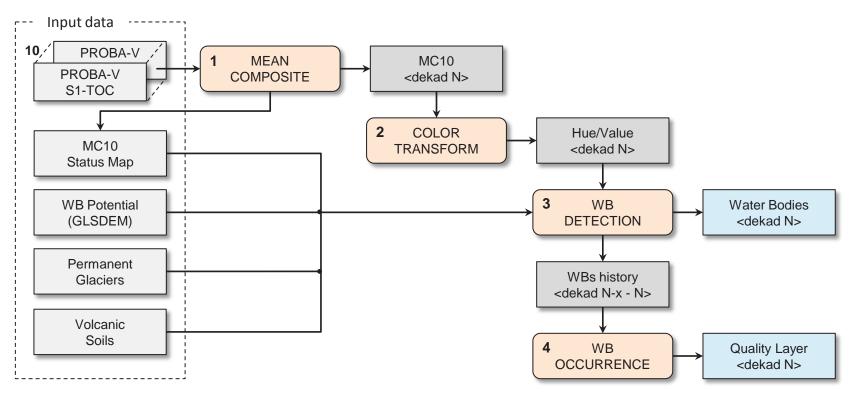
Spectral band	Wavelength (µm)
BLUE	0.477 - 0.493
RED	0.610 - 0.690
NIR	0.770 - 0.893
SWIR	1.570 - 1.650

- S1 TOC data at 1km spatial resolution (atmospheric correction: SMAC 4.0)

(Berthelot and Dedieu, 1998)



Water Body Detection Algorithm (WBDA) – General overview



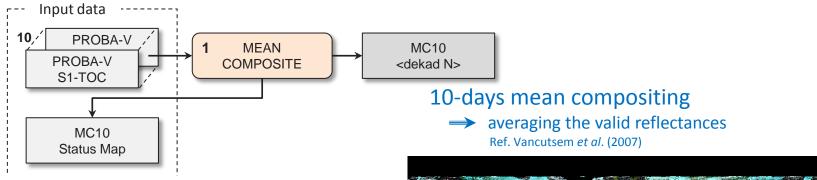
Main processing steps:

- mean compositing
- color transformation
- water body detection
- water body occurrence calculation



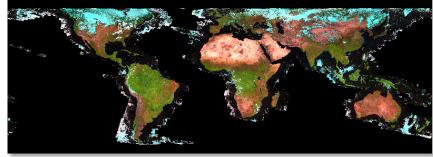
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Processing step 1: Mean Compositing



Bit Name Description 000: clear 010: undefine

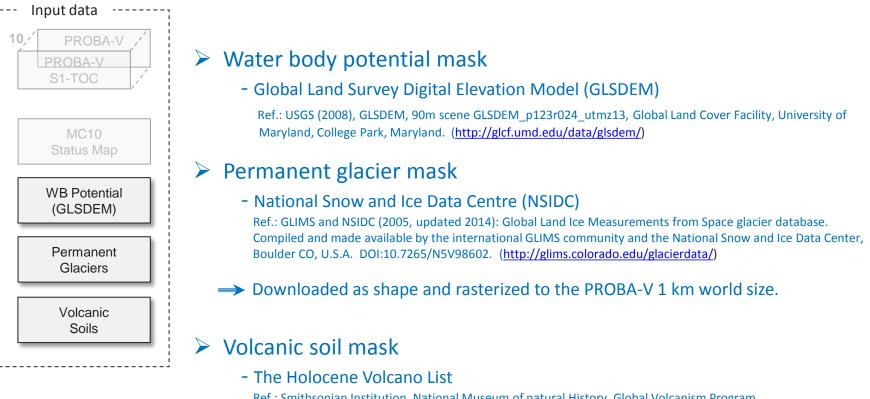
BR	Nume	Description
	Observation	000: clear
1 -3		010: undefined
		011: cloud
		100: snow / ice
4	_and/sea mask	0: sea
4	Lanu/sea mask	1: land
5	Mean composite SWIR quality flag	0: bad mean composite
5	Mean composite Swirk quality hag	1: good mean composite
6	Mean composite NIR quality flag	0: bad mean composite
0	Mean composite Mix quality hag	1: good mean composite
7	Mean composite RED quality flag	0: bad mean composite
I	Mean composite RED quality hag	1: good mean composite
8 (Most significant)	Mean composite BLUE quality flag	0: bad mean composite
o (iviosi significant)	Mean composite BLOE quality hay	1: good mean composite



01 Dec. 2013



WB detection - Input data



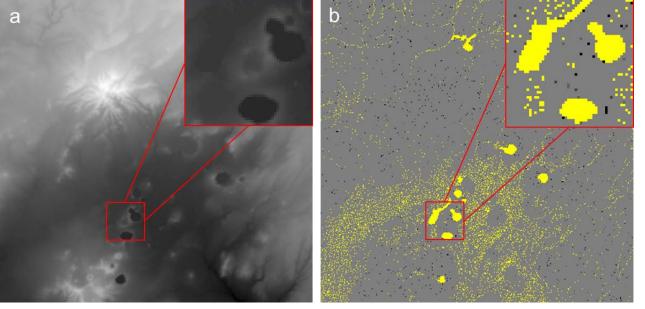
Ref.: Smithsonian Institution, National Museum of natural History, Global Volcanism Program. (<u>http://www.volcano.si.edu/</u>)

→ Delineated on Google Earth and rasterized to the PROBA-V 1 km world size.



Input data – Constructing the WB potential mask

1. Search for the lowest points in the terrain



Pixel elevation ≤ elevation of its eight neighbors

a) GLSDEM (\leftrightarrow 90 m; \ddagger 1 m)

b) detected lowest points

Detected pixels with 8 neighbors of equal elevation \rightarrow Level 1 otherwise \rightarrow Level 2

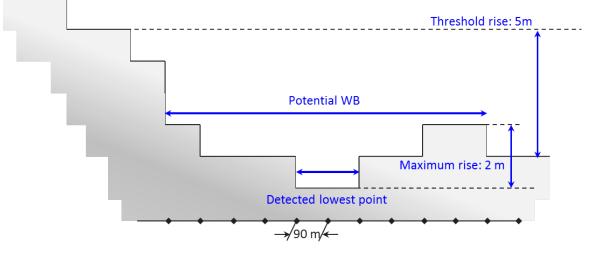


Input data – Constructing the WB potential mask

2. Filtering and expanding the detected lowest points



- the maximum rise of 5m is reached
- minimum size is 9 pixels



- Added pixels → Level 2



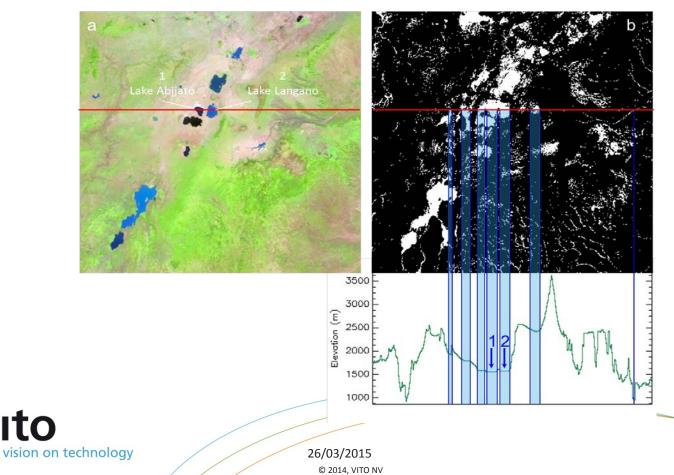
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Input data – Constructing the WB potential mask

3. Deriving the 1 km WBPM from the 90 m potential WBs

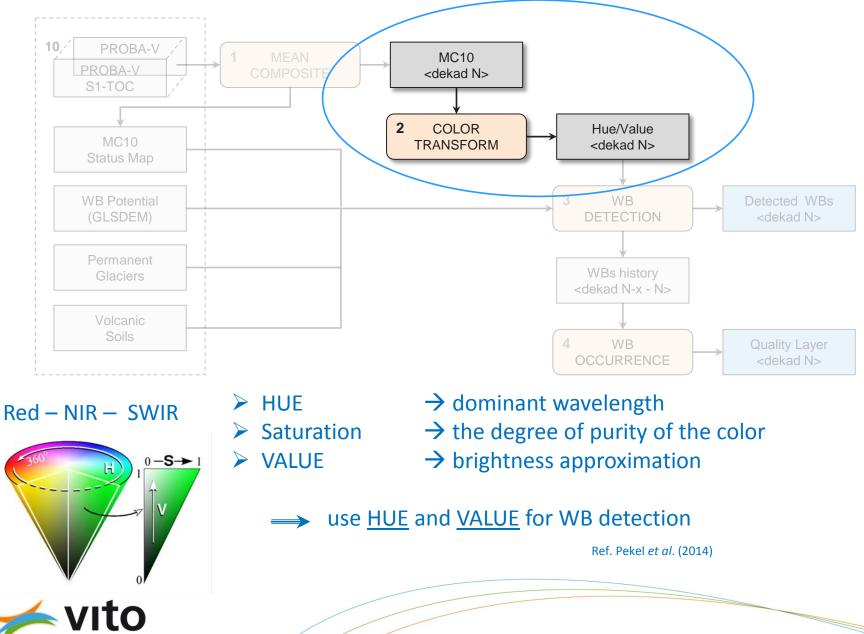
Set the WBPM pixel when:

- at least one of the corresponding pixels has 'Level 1'
- minimum 9 of corresponding pixels have 'Level 2'

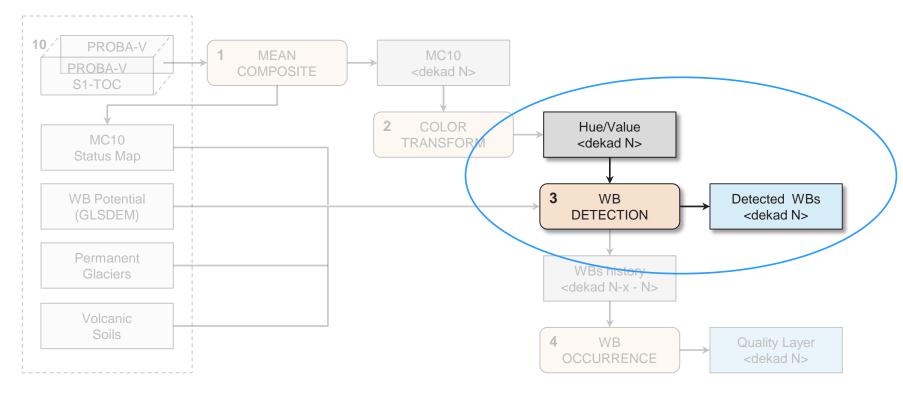


Processing step 2: HSV color transform

vision on technology



Processing step 3: Water Body detection



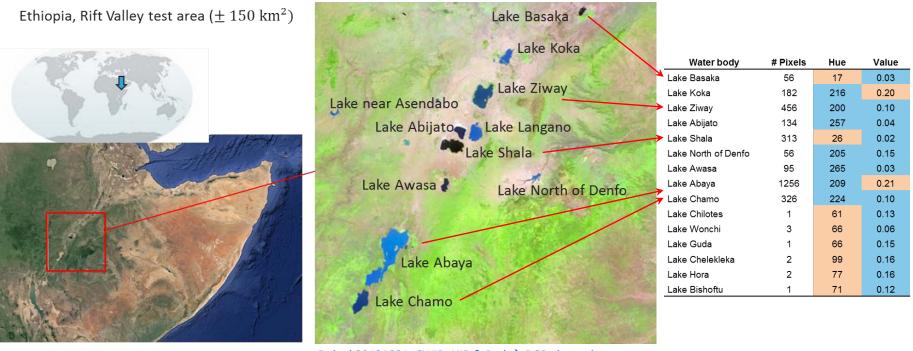
→ Defining the thresholds on HUE and VALUE

- Empirically & Iteratively



Water Body detection – The Ethiopian Rift Valley

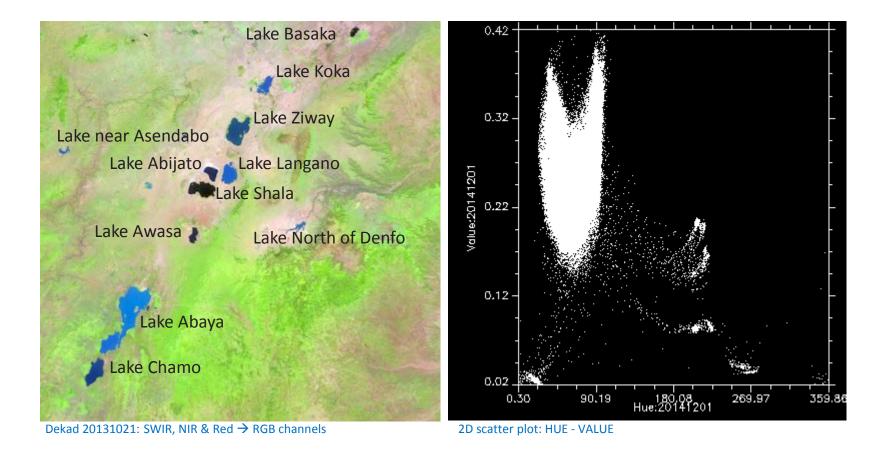
One of the focus areas for developing the WBDA Some typical values for HUE and VALUE



Dekad 20131021: SWIR, NIR & Red → RGB channels

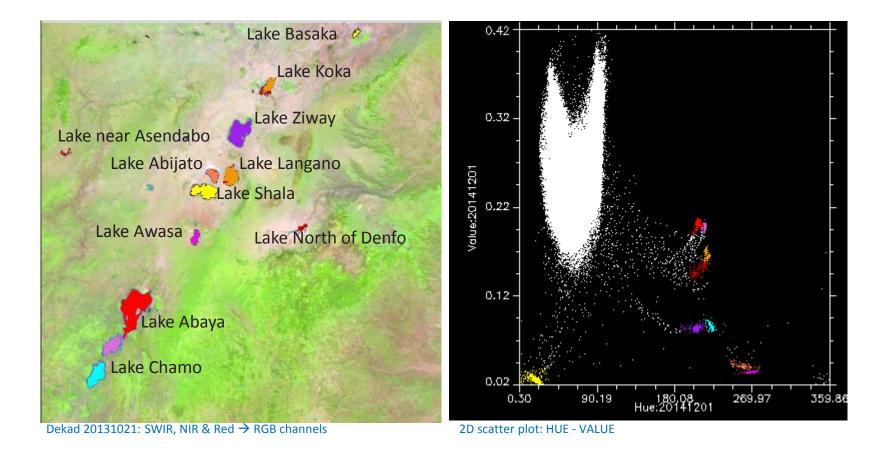


Water Body detection – Defining the thresholds





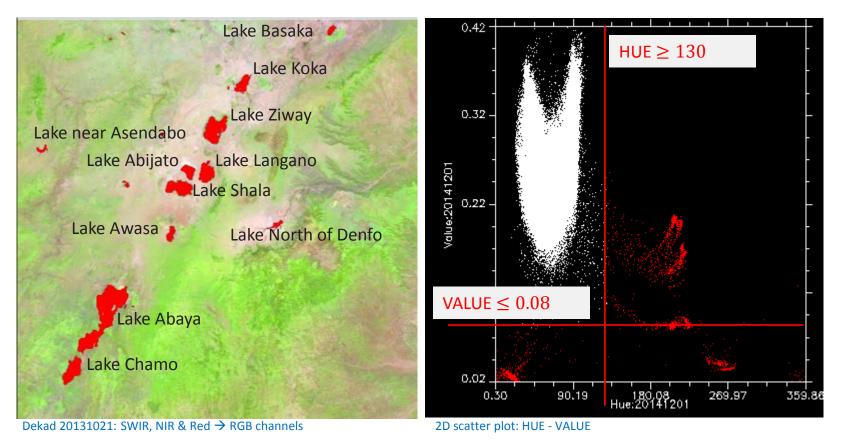
Water Body detection – Defining the thresholds





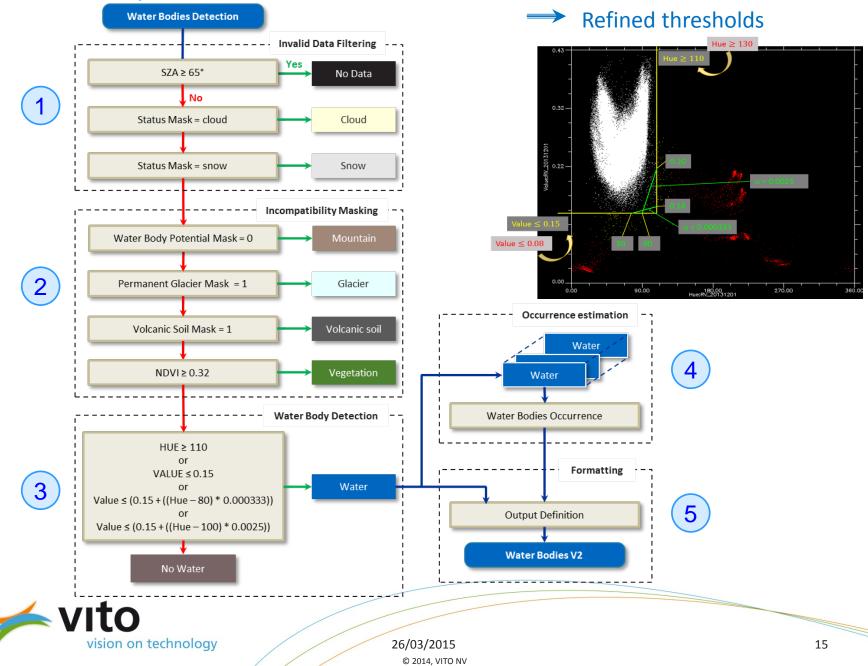
Water Body detection – Defining the thresholds

20 lakes are detected Further refining the thresholds considerably increased the commission errors



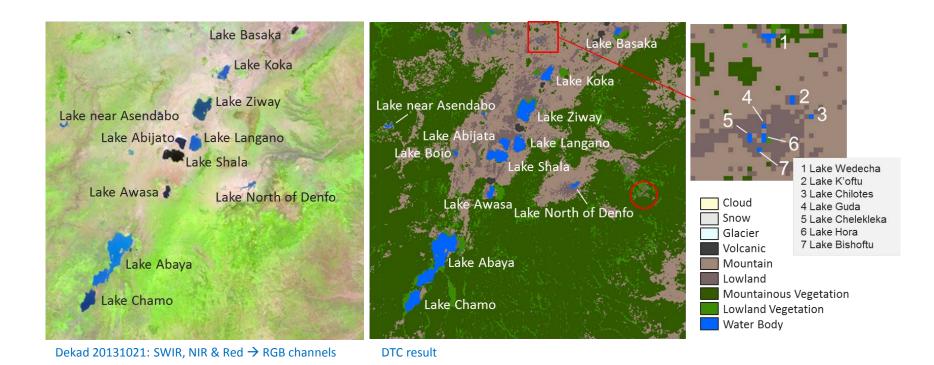


Water Body detection – Decision Tree Classification



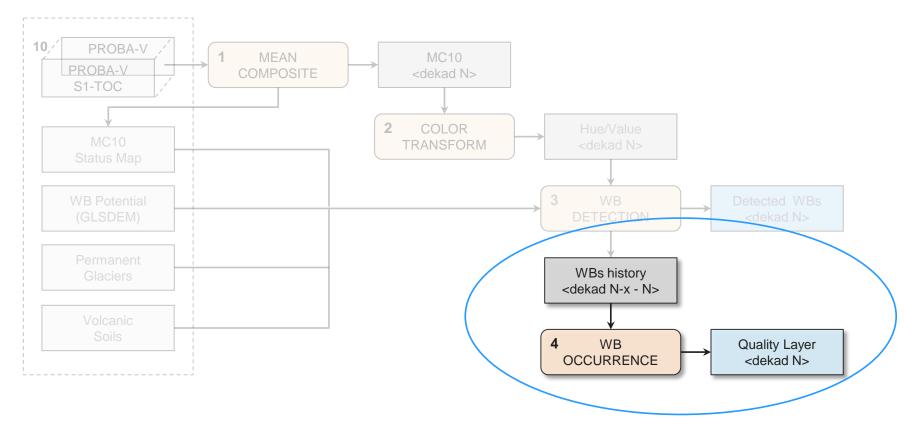
Water Body detection – Decision Tree Classification result

In total 32 WBs were detected on dekad 21 Oct. 2013 20 WBs were detected using the rough thresholds 12 WBs were detected using the refined thresholds





Water Body – Occurrence estimation



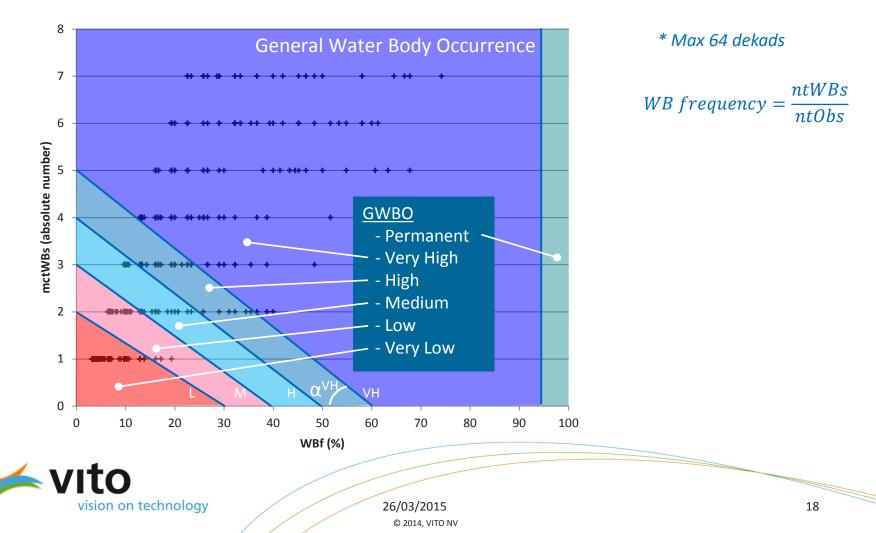
\implies To qualify the occurrence of the detected water bodies



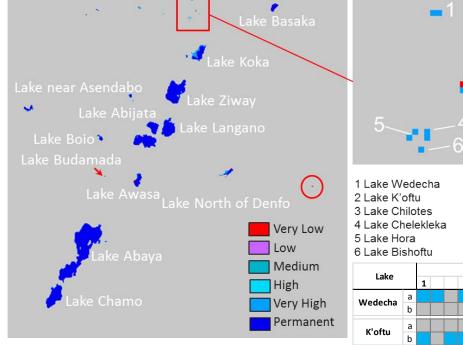
Water Body – Occurrence estimation

Deriving the General WB Occurrence using per pixel temporal-sequential statistics:

- Total number of temporal cloud free observations (ntObs)*
- Total number of temporal WB detections (*ntWBs*)
- Maximum number of continuous temporal WB detections (mctWBs)

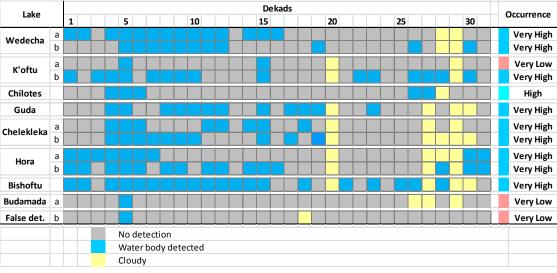


Water Body – Occurrence estimation



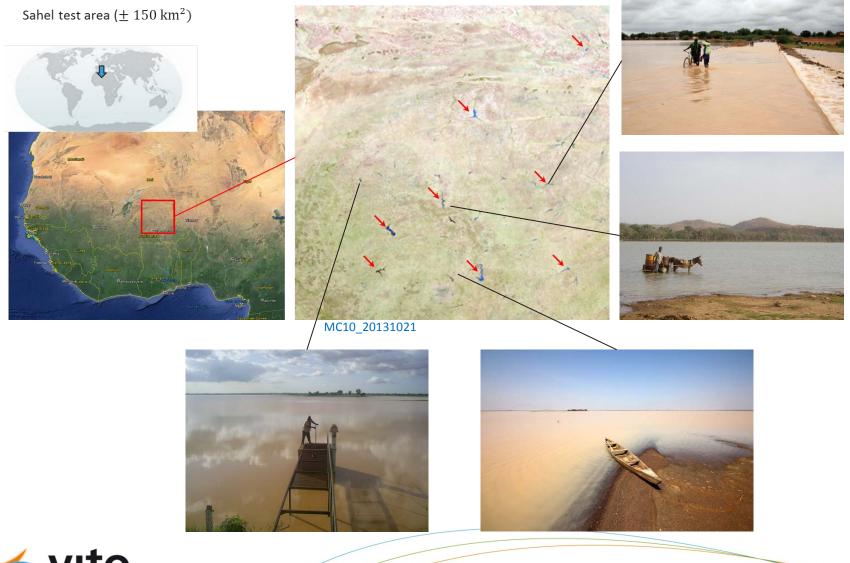
WB Occurrence – MC10_20131201

From MC10_20131021 (1) till MC10_20140821 (31)

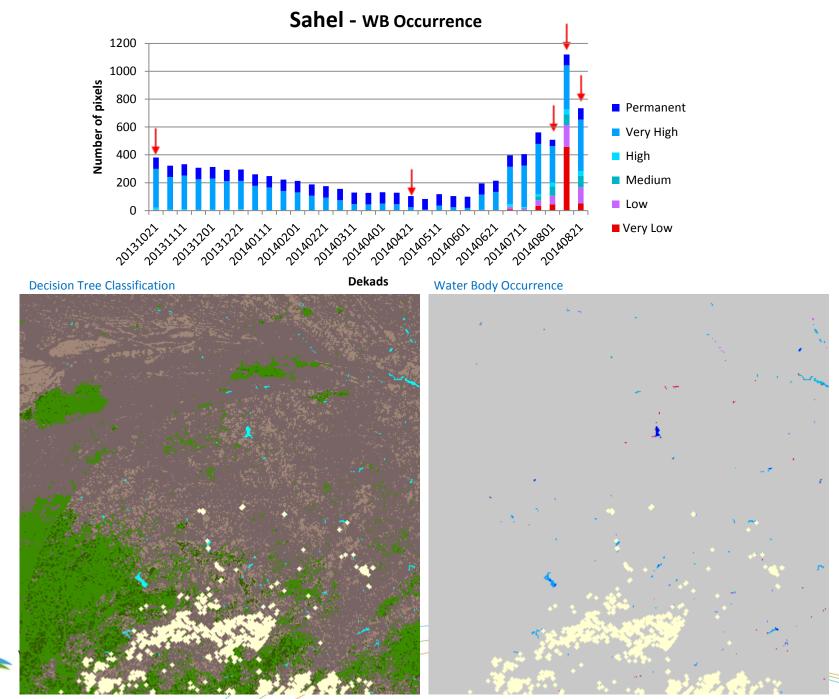




Water Body – The Sahel test area







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Water Body Detection – Conclusion

- Water body detection using HSV transformed Red NIR –SWIR bands proved to be successful (MODIS, Pekel 2014).
- > Applying the adapted WBDA to PROBA-V 1km revealed successful WB detection.
- Applying the Water Body Potential Mask considerable decreased the commission errors.
- The Water Body Occurrence reflects the history of the WBs and therefore adds additional information to the product.

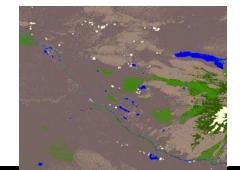
Water Body Detection – Upcoming

- Adapting the WBDA for historical SPOT-VGT processing (1999 2014)
- Adapting the WBDA for PROBA-V 300m & 100m processing





Questions?



2050



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MC10_20140521



Water Body – A first Quality Assessment

> Detailed observations of detected WBs on 7 areas selected worldwide

Validation using Google Earth (not always possible)

			- Len	
ld	Name	Lat	Lon	Remark / Observations
1	Sahel	15.611617	-3.2	Detected WBs show a good correlation with the rain season
2	South Africa	-27.665162	24.334789	Several WBs could not be validated (mining, salt planes ?)
3	India	26.566970	73.254424	Confusion with dark soils (not in the VSM)
4	China	36.084826	115.299060	Confusion with dark industrial areas, large cities \rightarrow SZA !
5	Argentina	-30.343735	-67.602697	Confusion with salt planes & desert \rightarrow flooded Yes/No ?
6	Canada	55.727680	-126.799116	Confusion with dense dark vegetation \rightarrow SZA & NDVI !
7	Poland	53.406252	14.629433	Small WBs masked due to adjacency with vegetation

Top - Left

A full quality assessment will be done according the Service Validation Plan [GIOGL1-SVP], for the year 2014.

